CROWD SIMULATION FOR EMERGENCY RESPONSE USING BDI AGENT BASED ON VIRTUAL REALITY

Based on a true story ...

Idea – what is going on ???

Simulation



Emergency response

Crowd





Virtual reality

BID AGENTS





Scenario

management of crowd evacuation under a truck bomb attack in an open public area



- AnyLogic: BDI framework (commercial ⊗)
- CAVE:Cave Automatic Virtual Environment

Human behavior in crowd

- Expanded BDI architecture:
- deliberator
- planner (reasoning processor)
- decision-executor
- confidence state

BDI agents – short review

- B = belifes
- D = desires
- I = intentions



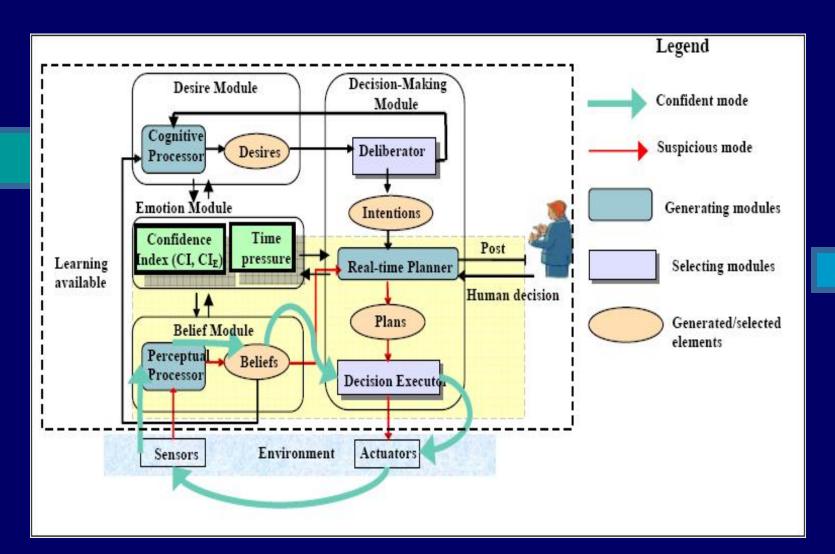


BDI agents – short review



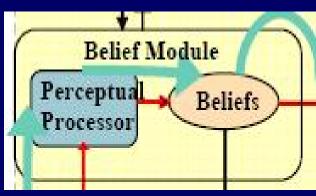
- Inteligent agent:
- autonomous
- cooperative
- learnable

Extended BDI architecture



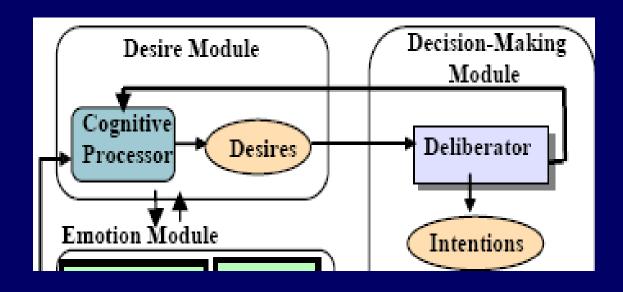
Perceptual processor

observes the environment
and tries to interpret
the data coming from
the sensors/external
environment.



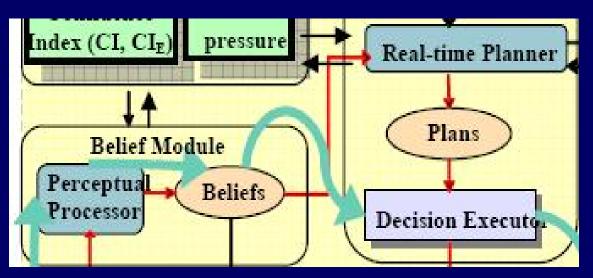
Deliberator

filters desires to select one intention.



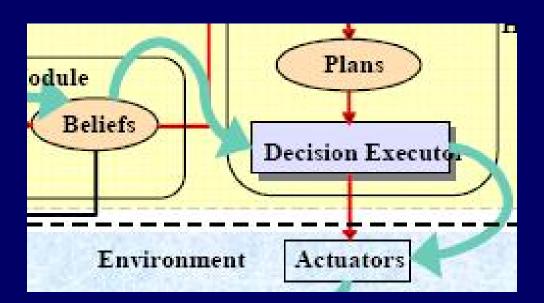
Real time planner

generates different plausible plans to achieve the selected intention based on the current beliefs.



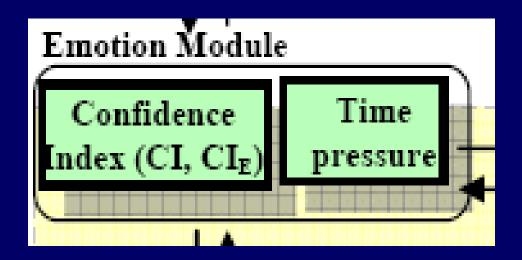
Decision executor

selects one of several plans generated by the real time planner

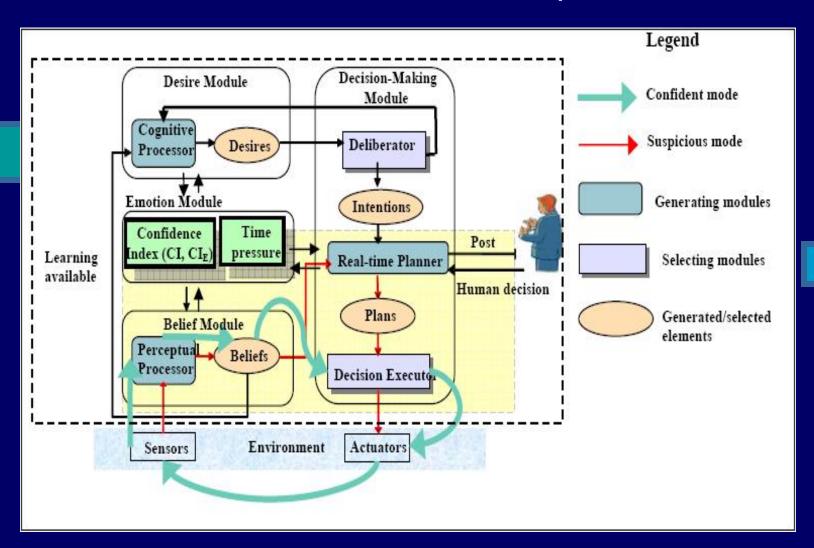


Confidence index

denotes the agent's optimism about achieving it's intentions



Extended BDI architecture, once more



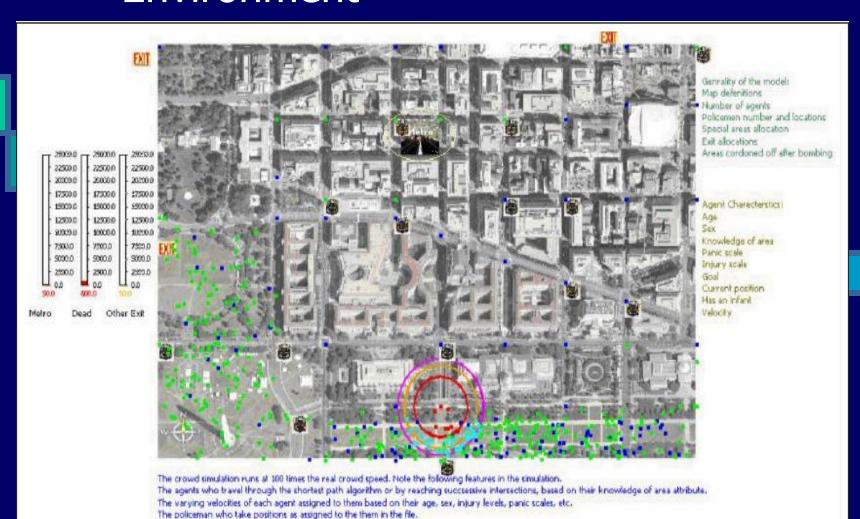
Environment





Environment

The policemen (first responders) who rush to the scene of the bombing.



Agent Characteristics

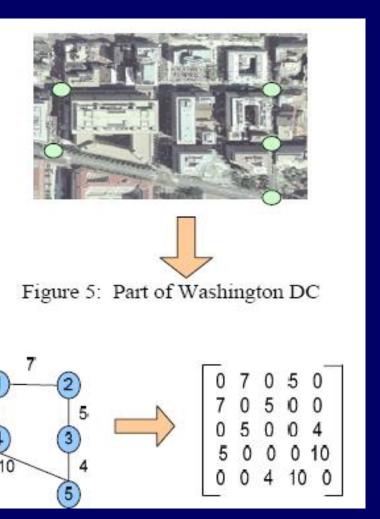
- different attributes to give each and every one an unique character set:
 - age
 - sex
 - knowledge of area
 - panic scale
 - leadership
 - independence
 - injury scale
 - current positions



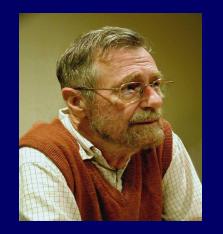
Major Data Structures

- network of roads = weighted graph with the vertices of the graph being intersections
- graph is represented as a distance matrix
- other areas = approximated rectangles.

Major Data Structures







- Dijkstra's algorithm is used to calculate the shortest path.
- The time complexity of Dijkstra's algorithm is O(|V|2)
 - |V| number of vertices in the graph.

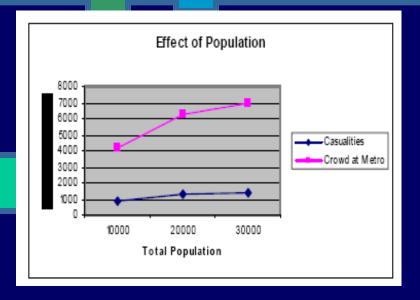
Experimentation and results

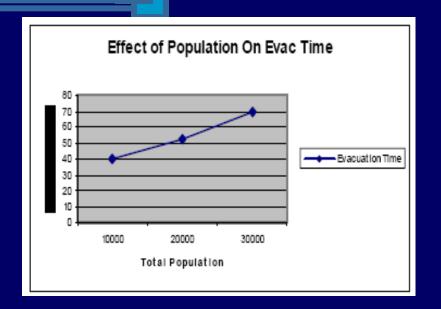
Table 1a: Weight Assignments

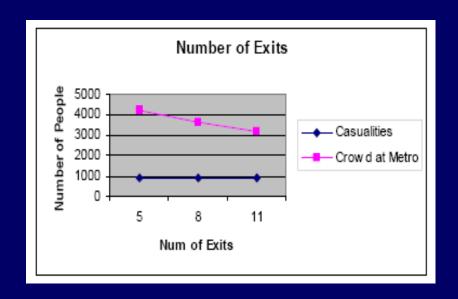
	Weight(15)	• /	Weight(15)
Danger paths	6	Short paths	4
Exit paths	4	Medium paths	9
Police paths	3	Long paths	2
Crowded paths	2		

Table 1b: Velocity Validation using VR

,	Avg Velocity	
Human1	5.08 m/s	
Human2	4.12 m/s	
Human3	4.36 m/s	







Authors of the article

- 4 guys from University of Arizona:
 - Ameya Shendarkar
 - Karthik Vasudevan
 - Seungho Lee
 - Young-Jun Son



